

# MAXIMIZE YOUR ROI WITH POS MV 320

POS MV 320 is a user-friendly, turnkey system designed and built to provide accurate attitude, heading, heave, position, and velocity data of your marine vessel and onboard sensors. POS MV is proven in all conditions, and is the georeferencing and motion compensation solution of choice for the hydrographic professional.

POS MV blends GNSS data with angular rate and acceleration data from an IMU and heading from the GPS Azimuth Measurement System (GAMS) to produce a robust and accurate full six degrees-of-freedom position and orientation solution.



## PERFORMANCE SUMMARY - POS MV 320 ACCURACY

POS MV 320	DGPS	RTK	Accuracy During GNSS Outage
Position	0.5 - 2 m¹	Horizontal: $+/-$ (8 mm + 1 ppm x baseline length) <sup>2</sup> Vertical: $+/-$ (15 mm + 1 ppm x baseline length) <sup>2</sup>	~ 6 m for 60 s total outages (DGPS) ~ 3 m for 60 s total outages (RTK) ~ 2 m for 60 s (post-processed DGNSS) ~ 1 m for 60 s total outages (IAPPK)
Roll & Pitch	0.02°	0.01° (0.008° with post processing)	0.02°
True Heading	0.01° with 4 m baseline 0.02° with 2 m baseline	-	1° per hour degradation (negligible for outages <60 s)
Heave TrueHeave™	5 cm or 5%³ 2 cm or 2%⁴	5 cm or 5%³ 2 cm or 2%⁴	5 cm or 5%³ 2 cm or 2%⁴

# **PCS OPTIONS**

COMPONENT	DIMENSIONS	WEIGHT	TEMPERATURE	HUMIDITY	POWER
Rack Mount PCS	L = 442mm, W = 356mm, H = 46mm	3.9 kg	-20 °C to +70 °C	10 - 80% RH	AC 120/230 V, 50/60 Hz, auto-switching 40 W
Small Form Factor PCS	L = 167mm, W = 185mm, H = 68mm	2.5 kg	-20 °C to +60 °C	0- 100% RH	DC 10-34 V, 35 W (peak)

# **INERTIAL MEASUREMENT UNIT (IMU)**

ENCLOSURE	DIMENSIONS	WEIGHT	TEMPERATURE	IP RATING
Between Decks	L = 158 mm, W = 158 mm, H = 124 mm	2.5 kg	-40 °C to +60 °C	IP65
Between Decks	L = 150 mm, W = 130 mm, H = 148 mm	2.8 kg	-40 °C to +60 °C	IP65
Submersible	Ø172 mm X 206 mm (base plate Ø209 mm)	3.9 kg	-40 °C to +60 °C	IP68

# GLOBAL NAVIGATION SATELLITE SYSTEM (GNSS)

COMPONENT	DIMENSIONS	WEIGHT	TEMPERATURE	HUMIDITY
GNSS Antenna	Ø178 mm, W = 73 mm	0.45 kg	-50 °C to +70 °C	0-100% RH

<sup>&</sup>lt;sup>1</sup> Depending on quality of differential corrections

<sup>&</sup>lt;sup>2</sup> Assumes 1 m IMU-GNSS antenna offset

<sup>&</sup>lt;sup>3</sup> Whichever is greater, for periods of 20 seconds or less

<sup>&</sup>lt;sup>4</sup> Whichever is greater, for periods of 35 seconds or less

#### 1. ETHERNET INPUT OUTPUT

Ethernet (10/100 base-T)

Parameters Time tag, status, position, attitude, heave,

 $velocity, track \, and \, speed, \, dynamics, \, perfor-$ 

mance metrics, raw IMU data, raw GNSS

data

Display Port Low rate (1 Hz) UDP protocol output

Control Port TCP/IP input for system commands

Primary Port Real-time (up to 200 Hz) UDP protocol

near-time (up to 200 Hz) ODF protoco

output

Secondary Port Buffered TCP/IP protocol output for data

logging to external device

#### 5. AUXILIARY GNSS INPUTS

Parameters NMEA Standard ASCII messages: \$GPGGA,

\$GPGST, \$GPGSA, \$GPGSV

Uses Aux input with best quality

Rate 1 Hz

#### 6. BASE GNSS CORRECTION INPUTS

Parameters RTCM V2.x, RTCM V3.x, CMR and CMR+,

CMRx input formats accepted. Combined with raw GNSS observables in navigation

solution

Rate 1 Hz

## 2. SERIAL RS232 INPUT OUTPUT

5 COM Ports User assignable to: NMEA output (0-5),

Binary output (0-5), Auxiliary GNSS input (0-2), Base GNSS correction input (0-2)

#### 7. DIGITAL I/O

1PPS 1 pulse-per-second Time Sync output,

normally high, active low pulse

Event Input (2) Time mark of external events. TTL pulses >

1 msec width, rising or falling edge, max rate

200 Hz

#### 3. NMEA ASCII OUTPUT

Parameters NMEA Standard ASCII messages:

Position (\$INGGA), Heading (\$INHDT), Track and Speed (\$INVTG), Statistics (\$INGST), Attitude (\$PASHR, \$PRDID), Time and Date

(\$INZDA, \$UTC)

Rate Up to 50 Hz (user selectable)

Configuration Output selections and rate individually

configurable on each assigned com port

#### 8. USER SUPPLIED EQUIPMENT

- PC for POSView Software (Required for configuration): Pentium 90 processor (minimum), 16 MB RAM, 1 MB free disk space, Ethernet adapter (RJ45 100 base T), Windows 98/2000/NT/XP/Windows 7

- PC for POSPac MMS Post-processing Software: Pentium III 800Mhz or equivalent (minimum), 512 MB RAM, 400 MB free disk space, USB Port (For Security Key), Windows XP or

Windows 7

## 4. HIGH RATE ATTITUDE OUTPUT

Parameters User selectable binary messages: attitude,

heading, speed

Rate Up to 200 Hz (user selectable)

Configuration Output selections and rate individually

configurable on each assigned com port

Scan the QR Code on your mobile device to access information on POS MV



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